# On the Existence of Solutions to Quasilinear Elliptic Equations with Perturbed Coefficients

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#### Abstract

Let  $Lu = -\sum_{i,j=1}^{N} a_{ij}(x,u)D_{ij}u + c(x,u)u$ ,  $c(x,r) \ge \alpha > 0$ . Consider the quasilinear elliptic equation  $Lu = f(x,u,\nabla u)$  on a bounded smooth domain  $\Omega$  in  $\mathbb{R}^N$ , where  $|f(x,r,\xi)| \le C_0 + h(|r|)|\xi|^{\theta}$ ,  $0 < \theta < 2$  and h is a locally bounded function. It is shown that if the oscillations of  $a_{ij}(x,r)$  with respect to r are sufficiently small on  $[-C_0/\alpha, C_0/\alpha]$  uniformly for x in  $\bar{\Omega}$ , then there exists a solution u in  $W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$ .

Keywords: quasilinear elliptic equation,  $W^{2,p}$  estimate,  $W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$  solution

#### 1 Introduction

Let  $\Omega$  be a bounded  $C^{1,1}$  domain in  $\mathbb{R}^N$ ,  $N \geq 3$ , and let  $L_v$ , L,  $D_v$ , D be elliptic operators defined by

$$L_{v}u = -\sum_{i,j=1}^{N} a_{ij}(x,v)D_{ij}u + c(x,v)u,$$

$$Lu = L_{u}u,$$

$$D_{v}u = -\sum_{i,j=1}^{N} D_{i}(a_{ij}(x,v)D_{j}u) + c(x,v)u, \text{ and}$$

$$Du = D_{u}u,$$

where  $\sum_{i,j=1}^{N} a_{ij}(x,r)\xi_i\xi_j \geq \lambda |\xi|^2$  for some positive constant  $\lambda$ . For a positive integer m and a real number  $p, p \geq 1$ , let

$$W^{m,p}(\Omega) = \{ u \in L^p(\Omega) : D^{\alpha}u \in L^p(\Omega) \text{ for } 0 < |\alpha| \le m \},$$
$$\|u\|_{m,p} = \left( \int_{\Omega} \sum_{|\alpha| \le m} |D^{\alpha}u|^p \right)^{\frac{1}{p}},$$

 $W_0^{m,p}(\Omega)$  be the closure of  $C_0^{\infty}(\Omega)$  in the space  $W^{m,p}(\Omega)$  and

$$H_0^1(\Omega) = W_0^{1,2}(\Omega).$$

Consider the quasilinear elliptic equation

$$Lu = f(x, u, \nabla u). \tag{1}$$

Under the assumptions of a priori bounds and oscillations with respect to x of all possible solutions in  $C^{2,\beta}(\bar{\Omega})$ , O. A. Ladyzhenskaya and N. N. Ural'tseva proved the existence of solutions in  $C^{2,\beta}(\bar{\Omega})$  for a general version of Equation (1) [7, p. 371]. If  $\Omega$  is a bounded domain (without smoothness constraints on the boundary) and  $a_{ij}$ , c are  $L^{\infty}$  functions, L. Boccardo, F. Murat and J. P. Puel [1] set up a weak maximum principle for approximating solutions in  $H_0^1(\Omega) \cap L^{\infty}(\Omega)$  to the elliptic equation in divergence form

$$Du = f(x, u, \nabla u), \tag{2}$$

where

$$|f(x,r,\xi)| \le C_0 + h(|r|)|\xi|^2$$
 (3)

with h being a locally bounded function defined on  $\mathbb{R}^+$ , and derived a solution in  $H_0^1(\Omega) \cap L^{\infty}(\Omega)$ . Furthermore, all solutions in  $H_0^1(\Omega) \cap L^{\infty}(\Omega)$  lie in  $[-C_0/\alpha, C_0/\alpha]$ .

 $L^{\infty}(\Omega)$ . Furthermore, all solutions in  $H_0^1(\Omega) \cap L^{\infty}(\Omega)$  lie in  $[-C_0/\alpha, C_0/\alpha]$ . It then arises readily to investigate  $W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$  solutions to (1). Let a fixed point x in  $\bar{\Omega}$  and an interval I in  $\mathbb{R}$  be given. We denote as  $\operatorname{osc} a_{ij}(x,r;I)$  the oscillations of  $a_{ij}(x,r)$  with respect to r, for r in I, that is

$$\operatorname{osc} a_{ij}(x, r; I) = \sup\{|a_{ij}(x, r_1) - a_{ij}(x, r_2)| : r_1, r_2 \in I\},\$$

and

$$\operatorname{osc} a(x, r; I) = \max_{1 \le i, j \le N} \operatorname{osc} a_{ij}(x, r; I).$$

In the light of the classical existence result of strong solutions in  $W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$  [3, p. 241] to the linear elliptic equation

$$L_0 u = -\sum_{i,j=1}^{N} a_{ij}(x) D_{ij} u + c(x) u = f(x), f \in L^p(\Omega),$$
(4)

[4] and [5] employed the perturbation method for  $W^{2,p}$  estimate of Equation (4) together with the weak maximum principle of [1] when  $a_{ij}$ , c depend on both x and r, and derived the existence result in  $W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$  provided osc  $a(x,r;\mathbb{R})$  is sufficiently small uniformly for x in  $\bar{\Omega}$  and

$$|f(x,r,\xi)| \le C_0 + h(|r|)|\xi|^{\theta} \text{ for } 0 < \theta < 2.$$
 (5)

Recently, the result in [6] improved the existence theorem of solutions for

$$f(x, r, \xi) = o[|r| + h(|r|)|\xi|^2].$$
(6)

This paper aims to extend the above results to the case that

$$|f(x,r,\xi)| \le C_0 + h(|r|)|\xi|^{\theta}, 0 < \theta < 2$$
 (7)

and

$$\operatorname{osc} a(x, r; [-C_0/\alpha, C_0/\alpha]) \le \frac{\lambda}{C_1}$$

for all x in  $\bar{\Omega}$ , where  $C_1$  depends on N, p and the diffeomorphism (see Lemma 1). Our main result in Theorem 1 proves the existence of strong solutions to (1). We shall also remark in Corollary 2 that the existence result to (2) remains valid if  $a_{ij}$  are independent of r on  $[-C_0/\alpha, C_0/\alpha]$ . The main idea relies on the  $L^{\infty}$  estimate of solutions to (2) and (1). Proposition 1 then carries out a priori bounds for the solutions when  $0 < \theta < 2$ .

### 2 Preliminaries

Let  $a_{ij}$ , their derivatives  $D_i a_{ij}$ ,  $D_r a_{ij}$  and c are bounded Carathodory functions, and  $c \ge \alpha$  for some positive number  $\alpha$ . For simplicity, we denote

$$I_0 = [-C_0/\alpha, C_0/\alpha],$$
 
$$W(\Omega) = W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega),$$
 
$$B_t = \{v \in W(\Omega) : ||v||_{2,p} \le t\}$$

and

$$g(v) = f(x, v, \nabla v)$$

and use C for a generic constant in this paper. Now assume that f is a Carathodory function defined on  $\Omega \times \mathbb{R} \times \mathbb{R}^N$  satisfying (7) and, for  $v \in W(\Omega)$ , consider the equation

$$L_v u = g(v) \tag{8}$$

in  $\Omega$ . If p is greater than N, then there exists a unique solution u in  $W(\Omega)$ . We start with a  $W^{2,p}$  estimate for the solutions in  $W(\Omega)$ . It is well known [3] that if  $u \in W^{2,p}(\Omega)$  and 1 , one has

$$||u||_{2,p} \le C(||u||_p + ||L_0u||_p).$$

For operators  $L_v$ , we quote the result from [4].

**Lemma 1.** Let  $\Omega$  be a bounded domain in  $\mathbb{R}^N$  which is  $C^{1,1}$  diffeomorphic to a ball in  $\mathbb{R}^N$ , and the coefficients  $a_{ij} \in C^{0,1}(\bar{\Omega} \times \mathbb{R})$ ,  $c \in L^{\infty}(\Omega \times \mathbb{R})$ ,  $|a_{ij}|$ ,  $|c| \leq \Lambda$  with  $\Lambda$  a positive constant,  $i, j = 1, \ldots, N$ . Then there exists a positive number  $C_1$  (depending on N, p and the diffeomorphism) such that if

$$ocite{occ} a(x, r; \mathbb{R}) \le \frac{\lambda}{C_1}$$

for all x in  $\bar{\Omega}$ , one has the estimate

$$||u||_{2,p} \le C(||L_v u||_p + ||u||_p) \tag{9}$$

for every u in  $W(\Omega)$  and  $L_v u$  belonging to  $L^p(\Omega)$ , 1 , where <math>C is a constant (independent of v) depending on  $N, p, \lambda, \Lambda, \partial\Omega, \Omega$ , the diffeomorphism and the moduli of continuity of  $a_{ij}(x,r)$  with respect to x in  $\Omega$ .

**Remark 1.** The magnitude of  $\operatorname{osc} a(x, r; \mathbb{R})$  fulfilling the purpose of Lemma 1 can be found in [8, p. 23] if  $\Omega$  is a ball in  $\mathbb{R}^N$  and in [4, p. 191] if  $\Omega$  is  $C^{1,1}$  diffeomorphic to a ball in  $\mathbb{R}^N$ .

**Remark 2.** One can derive (9) using interior and exterior estimates similar to those in the proof of Theorem 9.11 and Theorem 9.13 [3] with  $a_{ij}(x)$  replaced by  $a_{ij}(x, v(x))$ .

In view of Lemma 1, if u is a  $W(\Omega)$  solution to (8), then

$$||u||_{2,p} \le C(||g(v)||_p + ||u||_p). \tag{10}$$

Furthermore, an application of the weak maximum principle of A. D. Aleksandrov [3, p. 220] implies that

$$||u||_{\infty} \le C||\frac{g(v)}{\mathcal{D}^*}||_N,$$

where  $\mathcal{D}^*$  is the geometric mean of the eigenvalues of the matrix  $[a_{ij}]$ , and C depends on N and the diameter of  $\Omega$ . By ellipticity,  $\mathcal{D}^* \geq \lambda > 0$ , so

$$||u||_{p} \le C||g(v)||_{p}. \tag{11}$$

Combining (10) and (11), one gets

$$||u||_{2,p} \le C||g(v)||_p. \tag{12}$$

## 3 The Existence of Strong Solutions

In this section, we investigate the existence of strong solutions to (1) via the perturbation method, where f satisfies (7),  $0 < \theta < 2$ .

**Lemma 2.** The map  $\tilde{g}$  which assigns v in  $B_t$  to the  $W(\Omega)$  solution u of (8) is continuous in  $W^{1,p}(\Omega)$  if p is greater than N.

Proof. See 
$$[4, p. 196]$$
.

Also, we quote the following result of Theorem 2.1 in [1, p. 28].

Lemma 3. Assume that

$$|f_1(x,r,\xi)| \le C + k(|r|)|\xi|^2,$$

where k is an increasing function from  $\mathbb{R}^+$  into  $\mathbb{R}^+$ . If the solution u to

$$Du = f_1(x, u, \nabla u)$$

is in  $H_0^1(\Omega) \cap L^{\infty}(\Omega)$ , then it varifies

$$-\frac{C_0}{\alpha} \le u \le \frac{C_0}{\alpha}$$

almost everywhere in  $\Omega$ .

**Remark 3.** One can replace the increasing function k by a locally bounded function h in Lemma 3 by setting

$$k(|r|) = \sup\{h(|s|) : 0 \le s \le r\}.$$

Now, we reformulate (1),

$$Du = \tilde{f}(x, u, \nabla u),$$

where

$$\tilde{f}(x, u, \nabla u) = g(u) - [D_i a_{ij}(x, u) + D_r a_{ij}(x, u) D_i u] D_j u.$$

**Proposition 1.** If  $u \in W(\Omega)$  is a solution to (1) with the function f satisfying (7), then  $u(x) \in I_0$  almost everywhere in  $\Omega$ .

*Proof.* Let  $\epsilon$  be a sufficiently small positive number. By the inequality of arithmetic and gemetric means

$$\lambda_1 a_1 + \lambda_2 a_2 \ge a_1^{\lambda_1} a_2^{\lambda_2}$$

for positive numbers  $\lambda_1$ ,  $\lambda_2$  satisfying

$$\lambda_1 + \lambda_2 = 1$$
,

one gets

$$\lambda_1\frac{\epsilon}{h(|r|)} + \lambda_2 \left[\frac{h(|r|)}{\epsilon}\right]^{\frac{\lambda_1}{\lambda_2}} |\xi|^2 \geq \left[\frac{\epsilon}{h(|r|)}\right]^{\lambda_1} \left[\frac{h(|r|)}{\epsilon}\right]^{\frac{\lambda_1}{\lambda_2} \cdot \lambda_2} |\xi|^{2\lambda_2}.$$

When  $\lambda_2$  equals to  $\theta/2$ ,

$$h(|r|)|\xi|^{\theta} \le \epsilon + h_1(|r|)|\xi|^2,$$

where  $h_1$  is a locally bounded function, which in turn implies that

$$|\tilde{f}| \le C_0 + \epsilon + h_2(|r|)|\xi|^2$$

for some locally bounded function  $h_2$ . Since  $\epsilon$  is arbitrary, applying Remark 3 and Lemma 3, one concludes that u(x) lies in  $I_0$  almost everywhere in  $\Omega$  for every solution  $u \in W(\Omega)$  to Equation (1) with the function f satisfying (7).

It then suffices to examine the existence of strong solutions to (1) with  $a_{ij}(x,r)$  replaced by

$$b_{ij}(x,r) = \begin{cases} a_{ij}(x, \frac{-C_0}{\alpha - \alpha_0}), & \text{if } r < \frac{-C_0}{\alpha} \\ a_{ij}(x,r), & \text{if } \frac{-C_0}{\alpha} \le r \le \frac{C_0}{\alpha} \\ a_{ij}(x, \frac{C_0}{\alpha - \alpha_0}), & \text{if } r > \frac{C_0}{\alpha} \end{cases}$$
(13)

Denote  $\tilde{L}_v$  and  $\tilde{L}$  the elliptic operators defined by

$$\tilde{L}_{v}u = -\sum_{i,j=1}^{N} b_{ij}(x,v)D_{ij}u + c(x,v)u$$

and

$$\tilde{L}u = \tilde{L}_u u$$
.

Consider now the equation

$$\tilde{L}u = g(u) \tag{14}$$

in  $\Omega$ . Let  $g_n$  be the truncation of g by  $\pm n$ . For v in  $W^{1,p}(\Omega)$ , the Dirichlet problem

$$\tilde{L}_v u = g_n(v) \tag{15}$$

has a unique solution  $u_{n,v}$  in  $W(\Omega)$ . We note here that

$$\operatorname{osc} b_{ij}(x, r; \mathbb{R}) = \operatorname{osc} a_{ij}(x, r; I_0).$$

So if

$$\operatorname{osc} a(x, r; I_0) \leq \frac{\lambda}{C_1}$$

for x in  $\bar{\Omega}$ , the estimate (9) holds. Lemma 2 and the Schauder fixed point theorem imply that there exists a  $W(\Omega)$  solution  $u_n$  to the truncated equation

$$\tilde{L}u = g_n(u). \tag{16}$$

We proceed to the  $W^{2,p}$  estimate of  $(u_n)$ .

Lemma 4. If

$$\operatorname{osc} a(x, r; I_0) \le \frac{\lambda}{C_1}$$

for all x in  $\bar{\Omega}$ , then the approximating solutions  $(u_n)$  to (14) are  $W^{2,p}$  bounded.

*Proof.* Since f satisfies (7),

$$|g_n(u_n)| \le C_0 + \alpha_0 |u_n| + h(|u_n|)(C_\epsilon + \epsilon |\nabla u_n|^2).$$

Thus, by Proposition 1,

$$|g_n(u_n)| \le C + \epsilon |\nabla u_n|^2$$
.

Also, because each  $u_n$  belongs to  $L^{\infty}(\Omega) \cap W^{2,p}(\Omega)$ , from the Gagliardo-Nirenberg interpolation theorem [2, p. 194], we obtain

$$\|\nabla u_n\|_{2p}^2 \le C\|u_n\|_{\infty}\|u_n\|_{2,p}.$$

So

$$||g_n(u_n)||_p \le C + \epsilon ||u_n||_{2,p}.$$
 (17)

Combining (9) and (17), one deduces that

$$||u_n||_{2,p} \le C(||u_n||_p + ||g_n(u_n)||_p)$$
  
  $\le C + \epsilon ||u_n||_{2,p}.$ 

We get a  $W^{2,p}$  bounded sequence  $(u_n)$  if  $\epsilon$  is sufficiently small.

Once  $L^{\infty}$  and  $W^{2,p}$  bounds are established, the existence of solutions in  $W(\Omega)$  can be deduced as in the proof of Theorem 3.1 [4, p. 201]. For the sake of completion, we quote the proof in Theorem 1.

**Theorem 1.** Let  $\Omega$  be  $C^{1,1}$  smooth in  $\mathbb{R}^N$ ,  $N \geq 3$ ,  $a_{ij} \in C^{0,1}(\bar{\Omega} \times \mathbb{R})$ ,  $a_{ij}$ ,  $D_i a_{ij}$ ,  $D_r a_{ij}$ ,  $c \in L^{\infty}(\Omega \times \mathbb{R})$ . Then there exists a solution u in  $W(\Omega)$  to Equation (1) provided

$$oc a(x, r; I_0) \le \frac{\lambda}{C_1}$$

for all x in  $\bar{\Omega}$ .

Proof. By Lemma 4, we get  $W^{2,p}$  bounded approximating solutions to (14). It then follows from the compact imbedding  $W^{2,p}(\Omega) \to W^{1,p}(\Omega)$  that there exists a subsequence, still denoted by  $(u_n)$ , such that  $u_n \to u$ ,  $\nabla u_n \to \nabla u$  almost everywhere and  $u_n \to u$  in  $W_0^{1,p}(\Omega)$ . Now, since  $||u_n||_{2,p}$  are bounded by some positive quantity t and the set  $B_t$  is closed in  $W^{1,p}(\Omega)$ , the limit u of  $(u_n)$  belongs to  $W^{2,p}(\Omega)$ . By passing to the limit and using the Vitali Convergence Theorem, one deduces that  $\tilde{L}u_n \to \tilde{L}u$  in  $\mathfrak{D}(\Omega)$  and  $g_n(u_n) \to g(u)$  in  $L^1(\Omega)$  [1] which proves that u is a  $W(\Omega)$  solution to (14).

Finally, since solutions to (1) lie in  $I_0$  almost everywhere in  $\Omega$ ,  $a_{ij}(x, u(x))$  are equal to  $b_{ij}(x, u(x))$ . One concludes that u is in fact a solution to (1).

Corollary 1. There exists a solution in  $W(\Omega)$  to the elliptic equation (2) if  $a_{ij}$  are independent of r for  $|r| \leq C_0/\alpha$ .

*Proof.* In view of Proposition 1, consider Equation (2) with  $a_{ij}$  truncated by  $b_{ij}$  in (13), that is

$$-\sum_{i,j=1}^{N} D_i(b_{ij}(x,u)D_ju) + c(x,u)u = g(u).$$
(18)

Since  $a_{ij}$  are independent of r and  $b_{ij}(x,r)$  equal to  $a_{ij}(x,r)$  for r in  $I_0$ ,  $b_{ij}(x,r)$  can be written by  $b_{ij}(x)$  on  $I_0$ . Hence, (18) can be reformulated as

$$-\sum_{i,j=1}^{N} b_{ij}(x)D_{ij}u + c(x,u)u = \hat{f}(x,u,\nabla u),$$
(19)

where

$$\hat{f}(x, u, \nabla u) = g(u) + \sum_{i,j=1}^{N} D_i b_{ij}(x) D_j u.$$

One can then get a  $W^{2,p}$  bounded approximating solution sequence  $(u_n)$  to

$$-\sum_{i,j=1}^{N} b_{ij}(x)D_{ij}u + c(x,u)u = \hat{f}_n(x,u,\nabla u)$$

without assuming small oscillations of  $b_{ij}(x,r)$  to r. Applying the proof in Theorem 1, there exists a  $W(\Omega)$  solution u to (19). Finally, since solutions to (2) lie in  $I_0$  almost everywhere in  $\Omega$  and  $a_{ij}(x,u(x))$  equal to  $b_{ij}(x)$  for  $|u(x)| \leq C_0/\alpha$ , the solution u(x) to (19) in fact is a solution to (2).

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